GCE

## Mathematics (MEI)

## Advanced GCE 4763

Mechanics 3

## Mark Scheme for June 2010

| 1(a)(i) | $\mathrm{AP}=\sqrt{2.4^{2}+0.7^{2}}=2.5$ <br> Tension $T=70 \times 0.35 \quad(=24.5)$ <br> Resultant vertical force on P is $2 T \cos \theta-m g$ $\begin{aligned} & =2 \times 24.5 \times \frac{2.4}{2.5}-4.8 \times 9.8 \\ & =47.04-47.04=0 \end{aligned}$ <br> Hence $P$ is in equilibrium | $\begin{aligned} & \text { M1 } \\ & \text { A1 } \\ & \text { M1 } \\ & \text { B1 } \\ & \text { B1 } \\ & \text { E1 } \end{aligned}$ | 6 | Attempting to resolve vertically <br> For $T \times \frac{2.4}{2.5}$ (or $T \cos 16.3^{\circ} \mathrm{etc}$ ) <br> For $4.8 \times 9.8$ <br> Correctly shown |
| :---: | :---: | :---: | :---: | :---: |
| (ii) | $\mathrm{EE}=\frac{1}{2} \times 70 \times 0.35^{2}$ <br> Elastic energy is 4.2875 J | $\begin{aligned} & \text { M1 } \\ & \text { A1 } \end{aligned}$ | 2 | (M0 for $\frac{1}{2} \times 70 \times 0.35$ ) <br> Note If 70 is used as modulus instead of stiffness: (i) M1A0M1B1B1E0 <br> (ii) M1 A1 for 1.99 |
| (iii) | Initial $\mathrm{KE}=\frac{1}{2} \times 4.8 \times 3.5^{2}$ <br> By conservation of energy $\begin{aligned} 4.8 \times 9.8 h & =2 \times 4.2875+\frac{1}{2} \times 4.8 \times 3.5^{2} \\ 47.04 h & =8.575+29.4 \end{aligned}$ <br> Height is 0.807 m ( 3 sf ) | $\begin{aligned} & \hline \text { B1 } \\ & \text { M1 } \\ & \text { F1 } \\ & \text { A1 } \end{aligned}$ | 4 | Equation involving EE, KE and PE <br> (A0 for 0.8$) \quad \mathrm{ft}$ is $\frac{2 \times(\mathrm{ii})+29.4}{47.04}$ |
| (b)(i) | $\begin{aligned} & {[\text { Force }]=\mathrm{MLT}^{-2}} \\ & {[\text { Stiffness }]=\mathrm{MT}^{-2}} \end{aligned}$ | $\begin{aligned} & \mathrm{B} 1 \\ & \mathrm{~B} 1 \end{aligned}$ | 2 | Deduct 1 mark if units are used |
| (ii) | $\begin{aligned} \mathrm{LT}^{-1} & =\mathrm{M}^{\alpha}\left(\mathrm{MT}^{-2}\right)^{\beta} \mathrm{L}^{\gamma} \\ \gamma & =1 \\ \beta & =\frac{1}{2} \\ 0 & =\alpha+\beta \\ \alpha & =-\frac{1}{2} \end{aligned}$ | $\begin{aligned} & \mathrm{B} 1 \\ & \mathrm{~B} 1 \\ & \mathrm{M} 1 \\ & \mathrm{~A} 1 \end{aligned}$ |  | Considering powers of M <br> When [Stiffness] is wrong in (i), allow all marks ft provided the work is comparable and answers are non-zero |

\begin{tabular}{|c|c|c|c|c|}
\hline 2 (i) \& \begin{tabular}{l}
\(R \cos \theta=m g \quad\) [ \(\theta\) is angle between OB and vertical ]
\[
R \times 0.8=0.4 \times 9.8
\] \\
Normal reaction is 4.9 N
\end{tabular} \& M1
A1
A1 \& 3 \& Resolving vertically \\
\hline (ii) \& \begin{tabular}{l}
\[
\begin{align*}
R \sin \theta \& =m \frac{v^{2}}{r} \\
4.9 \times 0.6 \& =0.4 \times \frac{v^{2}}{1.5} \\
v^{2} \& =11.025 \tag{3sf}
\end{align*}
\] \\
Speed is \(3.32 \mathrm{~m} \mathrm{~s}^{-1}\)
\end{tabular} \& M1
A1

A1 \& \& | For acceleration $\frac{v^{2}}{r}$ or $r \omega^{2}$ or $4.9 \times 0.6=0.4 \times 1.5 \omega^{2}$ |
| :--- |
| ft is $1.5 \sqrt{R}$ | <br>

\hline (iii) \& By conservation of energy

$$
\begin{aligned}
\frac{1}{2} m u^{2} & =m g \times 2.5 \\
u^{2} & =5 g \quad(u=7) \\
R-m g & =m \times \frac{u^{2}}{2.5} \\
R-m g & =2 m g \\
R & =3 m g
\end{aligned}
$$ \& M1

A1
M1

E1 \& \& | Equation involving KE and PE |
| :--- |
| Vertical equation of motion (must have three terms) |
| Correctly shown or $R=11.76$ and $3 \times 0.4 \times 9.8=11.76$ | <br>

\hline \[
$$
\begin{aligned}
& \text { (iv) } \\
& \text { (v) }
\end{aligned}
$$

\] \& | $\begin{aligned} \frac{1}{2} m v^{2} & =m g \times 2.5 \cos \theta \\ v^{2} & =5 g \cos \theta \end{aligned}$ $R-m g \cos \theta=m \times \frac{v^{2}}{2.5}$ |
| :--- |
| When $R=2 \mathrm{mg}$ ( $=7.84$ ) , $\begin{aligned} 2 m g-m g \cos \theta & =\frac{m v^{2}}{2.5} \\ 2 m g-\frac{m v^{2}}{5} & =\frac{m v^{2}}{2.5} \\ 7.84-0.08 v^{2} & =0.16 v^{2} \\ v^{2} & =\frac{98}{3} \end{aligned}$ |
| Speed is $5.72 \mathrm{~ms}^{-1}$ |
| (3 sf) |
| $\cos \theta=\frac{v^{2}}{5 g}=\frac{2}{3} \quad\left(\theta=48.2^{\circ}\right.$ or 0.841 rad$)$ |
| Tangential acceleration is $g \sin \theta$ |
| Tangential acceleration is $7.30 \mathrm{~ms}^{-2}$ | \&  \& \& | Mark (iv) and (v) as one part Equation involving KE, PE and an angle ( $\theta$ is angle with vertical) [ $\frac{1}{2} m v^{2}=m g h$ can earn M1A1, but only if $\cos \theta=h / 2.5$ appears somewhere ] |
| :--- |
| Equation of motion towards O (must have three terms, and the weight must be resolved) |
| Obtaining an equation for $v$ Obtaining an equation for $\theta$ These two marks are each dependent on M1M1 above |
| [ $g \sin \theta$ in isolation only earns M1 if the angle $\theta$ is clearly indicated ] | <br>

\hline
\end{tabular}

| 3 (i) | Volume is $\begin{aligned} &=\pi\left[-\frac{1}{x}\right]_{1}^{5}\left(=\frac{4}{5} \pi\right) \\ & \int \pi x y^{2} \mathrm{~d} x=\int_{1}^{5} \pi x\left(\frac{1}{x}\right)^{2} \mathrm{~d} x \\ &=\pi[\ln x]_{1}^{5} \quad(=\pi \ln 5) \\ & \bar{x}=\frac{\pi \ln 5}{\frac{4}{5} \pi}=\frac{5 \ln 5}{4} \quad(2.012) \end{aligned}$ | M1 <br> A1 <br> M1 <br> A1 <br> A1 | $\pi$ may be omitted throughout Limits not required <br> For $-\frac{1}{x}$ <br> Limits not required <br> For $\ln x$ <br> $S R$ If exact answers are not seen, deduct only the first A1 affected |
| :---: | :---: | :---: | :---: |
| (ii) |  | M1 <br> A1 <br> M1 <br> A1 <br> M1 <br> A1 <br> A1 | Limits not required <br> For $\ln x$ <br> Limits not required <br> For $\int\left(\frac{1}{x}\right)^{2} \mathrm{~d} x$ <br> For $-\frac{1}{2 x}$ |
| (iii) | CM of $R_{2}$ is $\left(\frac{2}{5 \ln 5}, \frac{4}{\ln 5}\right)$ | B1B1 ft | Do not penalise inexact answers in this part |
| (iv) | $\begin{aligned} & \bar{x}=\frac{(\ln 5)\left(\frac{4}{\ln 5}\right)+(\ln 5)\left(\frac{2}{5 \ln 5}\right)+(1)\left(\frac{1}{2}\right)}{\ln 5+\ln 5+1} \\ & \text { CM is }\left(\frac{4.9}{2 \ln 5+1}, \frac{4.9}{2 \ln 5+1}\right) \quad(1.161,1.161) \end{aligned}$ | B1 <br> M1 <br> M1 <br> A1 cao | For CM of $R_{3}$ is $\left(\frac{1}{2}, \frac{1}{2}\right)$ <br> (one coordinate is sufficient) Using $\sum m x$ with three terms Using $\frac{\sum m x}{\sum m}$ with at least two terms in each sum |


| 4 (i) | $\left\{\begin{aligned} v=\frac{\mathrm{d} x}{\mathrm{dt} t} & =A \omega \cos \omega t-B \omega \sin \omega t \\ a=\frac{\mathrm{d}^{2} x}{\mathrm{~d} t^{2}} & =-A \omega^{2} \sin \omega t-B \omega^{2} \cos \omega t \\ & =-\omega^{2}(A \sin \omega t+B \cos \omega t)=-\omega^{2} x \end{aligned}\right.$ | $\begin{aligned} & \text { B1 } \\ & \text { M1 } \\ & \text { E1 } \end{aligned}$ | 3 | Finding the second derivative <br> Correctly shown |
| :---: | :---: | :---: | :---: | :---: |
| (ii) | $\begin{aligned} & B=-16 \\ & \omega=0.25 \\ & A=30 \end{aligned}$ | $\begin{aligned} & \text { B1 } \\ & \text { B1 } \\ & \text { B2 } \end{aligned}$ |  | When $A$ is wrong, give B 1 for a correct equation involving $A$ [e.g. $A \omega=7.5$ or $\left.7.5^{2}=\omega^{2}\left(A^{2}+B^{2}-16^{2}\right)\right]$ or for $A=-30$ |
| (iii) | Maximum displacement is $( \pm) \sqrt{A^{2}+B^{2}}$ <br> Maximum displacement is 34 m <br> Maximum speed is ( $\pm$ ) $34 \omega$ <br> Maximum acceleration is $( \pm) 34 \omega^{2}$ <br> Maximum speed is $8.5 \mathrm{~m} \mathrm{~s}^{-1}$ <br> Maximum acceleration is $2.125 \mathrm{~ms}^{-2}$ | $\begin{aligned} & \text { M1 } \\ & \text { A1 } \\ & \text { M1 } \\ & \text { F1 } \\ & \text { F1 } \end{aligned}$ | 5 | Or $7.5^{2}=\omega^{2}\left(\mathrm{amp}^{2}-16^{2}\right)$ <br> Or finding $t$ when $v=0$ and substituting to find $x$ <br> For either (any valid method) <br> Only ft from $\omega \times$ amp <br> Only ft from $\omega^{2} \times$ amp |
| (iv) | $\begin{aligned} & v=7.5 \cos 0.25 t+4 \sin 0.25 t \\ & \text { When } t=15, v=7.5 \cos 3.75+4 \sin 3.75 \\ & =-8.44 \end{aligned}$ <br> Speed is $8.44 \mathrm{~m} \mathrm{~s}^{-1}(3 \mathrm{sf})$; downwards | M1 <br> A1 | 2 |  |
| (v) | Period $\frac{2 \pi}{\omega} \approx 25 \mathrm{~s}$, so $t=0$ to $t=15$ is less than one period When $t=15, x=30 \sin 3.75-16 \cos 3.75$ $=-4.02$ <br> Distance travelled is $16+34+34+4.02$ <br> Distance travelled is 88.0 m ( 3 sf ) | M1 <br> M1 <br> M1 <br> A1 cao | 4 | Take account of change of direction Fully correct strategy for distance |

